TEST #2
STA 4853
May 1, 2015

Please read the following directions.
DO NOT TURN THE PAGE UNTIL INSTRUCTED TO DO SO

Directions

- This exam is **closed book** and **closed notes**.
- There are 27 questions.
- Circle a **single** answer for each multiple choice question. Your choice should be made clearly.
- On the multiple choice questions, always **circle the correct response**. (Sometimes the question has an empty blank or a box, but this is **NOT** where the answer goes.)
- There is no penalty for guessing.
- The exam has 10 pages.
- Each question is worth equal credit.

The next two problems involve this situation:

Suppose you have chosen to model time series data z_1, z_2, \ldots, z_n using an AR(1) process $z_t = C + \phi_1 z_{t-1} + a_t$ with C = 1, $\phi_1 = 0.8$, and $\sigma_a = 1.5$. You decide to forecast future values z_{n+1} , z_{n+2}, z_{n+3}, \ldots of this time series.

Problem 1. As you forecast further and further into the future, the long run forecasts \widehat{z}_{n+k} will _____

- a) continue to gradually increase indefinitely
- **b**) be white noise
- c) be a random walk
- d) continue to gradually decrease indefinitely
- e) converge to a straight line with non-zero slope
- f) converge to a repeating pattern
- g)★ converge to a limiting constant

Problem 2. The confidence interval widths for the long run forecasts will _____

- a) continue to gradually increase indefinitely
- **b**) be white noise
- c) be a random walk
- d) continue to gradually decrease indefinitely
- e) converge to a straight line with non-zero slope
- f) converge to a repeating pattern
- g)★ converge to a limiting constant

Problem 3. The ARMA(2,2) process

$$z_t = C + \phi_1 z_{t-1} + \phi_2 z_{t-2} + a_t - \theta_1 a_{t-1} - \theta_2 a_{t-2}$$

will be invertible if _____

- a) $|\theta_1| < 1$
- **b**) $|\phi_1| < 1$
- c) the roots of the MA polynomial are strictly inside the unit circle
- \mathbf{d}) the roots of the AR polynomial are strictly inside the unit circle
- e)* $|\theta_2| < 1$, $\theta_2 + \theta_1 < 1$, and $\theta_2 \theta_1 < 1$
 - f) $|\phi_2| < 1$, $\phi_2 + \phi_1 < 1$, and $\phi_2 \phi_1 < 1$

Problem 4. Suppose you wish to construct a transfer function model explaining the response series Y_t in terms of the input series X_t . You find that X_t and Y_t are not jointly stationary, but, after differencing, the differenced series $X_t^* = (1-B)X_t$ and $Y_t^* = (1-B)Y_t$ are jointly stationary. You then identify a transfer function and ARMA noise model for the differenced series which is

$$Y_t^* = \frac{B^b \omega(B)}{\delta(B)} X_t^* + \frac{\theta(B)}{\phi(B)} a_t.$$

In terms of the original series X_t and Y_t , this model may be written as ____

$$\mathbf{a}) Y_t = \frac{B^b \omega(B)}{\delta(B)} X_t + \frac{(1-B)\theta(B)}{\phi(B)} a_t.$$

$$\mathbf{b}) \star Y_t = \frac{B^b \omega(B)}{\delta(B)} X_t + \frac{\theta(B)}{(1 - B)\phi(B)} a_t.$$

$$\mathbf{c}) Y_t = \frac{B^b \omega(B)}{\delta(B)} (1 - B) X_t + \frac{\theta(B)}{\phi(B)} a_t.$$

$$\mathbf{d}) Y_t = \frac{B^b \omega(B)}{(1 - B)\delta(B)} X_t + \frac{\theta(B)}{\phi(B)} a_t.$$

$$\mathbf{e}) \ (1-B)Y_t = \frac{B^b \omega(B)}{\delta(B)} X_t + \frac{\theta(B)}{\phi(B)} a_t.$$

$$\mathbf{f}) \ \frac{Y_t}{1-B} = \frac{B^b \omega(B)}{\delta(B)} X_t + \frac{\theta(B)}{\phi(B)} a_t \,.$$

After fitting a time series model, the plot of the residuals versus the one-step-ahead forecasts is often used to determine if the

- a) mean of the series varies with time
- **b)** ACF of the series varies with time
- c) residuals are normally distributed
- d)★ variability of the residuals changes with the level of the series
 - e) one-step-ahead forecasts change with the level of the series
 - f) series needs further differencing
 - g) one-step-ahead forecasts are normally distributed

For a specified ARIMA(p, d, q) process z_t , suppose you know all the values of the series z_t and the random shocks a_t for times $t \leq n$ (call this information set \mathcal{I}_n), and you wish to predict future values z_{n+k} . If you are using "squared error loss," then the best predictions \widehat{z}_{n+k} are given by $\hat{z}_{n+k} = \underline{\hspace{1cm}}$

$$\mathbf{a})\star\ E(z_{n+k}\,|\,\mathcal{I}_n)$$

b)
$$\operatorname{Var}(z_{n+k} \mid \mathcal{I}_n)$$

b)
$$Var(z_{n+k} | \mathcal{I}_n)$$
 c) $\sigma_a \sqrt{1 + \psi_1^2 + \dots + \psi_k^2}$

d)
$$z_n$$
 (the last known value) **e**) a_n **f**) \widehat{z}_n

$$\mathbf{e}) a_i$$

$$\mathbf{f}$$
) \widehat{z}_r

$$\mathbf{g}) 0$$

Problem 7. Suppose you are modeling a long time series (of length n) named Z, you have chosen the correct model, and the parameter estimates are accurate. The output file created by the FORECAST statement contains columns with the headings Z, FORECAST, STD, L95, U95, and RESIDUAL. Prior to time n (the end of the series), you expect of the values in column to lie between the values in columns L95 and U95. (Circle the choice below with the responses that best complete the two blanks.)					
$\mathbf{a})$	about 95%, FORECAS	Т			
,	less than 95%, FOREC				
$\mathbf{c})$	nearly all, Z				
d)*	about 95%, Z				
$\mathbf{e})$	about 95%, RESIDUA	L			
\mathbf{f})	nearly all, RESIDUAL				
\mathbf{g}	more than 95%, RES.	IDUAL			
\mathbf{h}	about 95%, STD				
i)	nearly all, STD				
1. 2. 3. 4. 5.	Try a model without Try differencing at la Try replacing differen	ag 1 a second time. noting at lag 1 by differently which includes a season on ∇z_t .	ncing at lag 4.	nay be reasonable.)	
	t the pair of options to the list about		able and circle you	r choice below . (Do NOT	
	a) 1 or 2	b) 1 or 5	c) 1 or 6	d) 5 or 6	
	e)★ 3 or 4	f) 3 or 5	g) 2 or 5	h) 2 or 6	
force	d to pay \$100 unless		ithin ε of X (where	formation \mathcal{I} . If you will be ε is small), then your best \mathcal{I} .	
	$\mathbf{a})\star \text{ mode}$	b) variance	c) star	ndard deviation	
	\mathbf{d}) mean	$\mathbf{e})$ median	\mathbf{f}) minimum	\mathbf{g}) P -value	

Problem 10. In PROC ARIMA, an ESTIMATE statement which includes

$$INPUT = (3\$(1,2)/(1)X)$$

is instructing SAS to use a transfer function of the form _____

a)
$$\frac{(1-B^3)(\omega_1 B - \omega_2 B^2)}{1 - \delta_1 B} X_t$$

$$\mathbf{b})\star \ \frac{B^3(\omega_0 - \omega_1 B - \omega_2 B^2)}{1 - \delta_1 B} X_t$$

$$\mathbf{c}) \ \frac{B^3(1-\omega_1 B - \omega_2 B^2)}{\delta_0 - \delta_1 B} X_t$$

$$\mathbf{d}) \ \frac{3B(1-\omega_1 B - \omega_2 B^2)}{\delta_0 - \delta_1 B} X_t$$

e)
$$\frac{(1-B^3)(\omega_1 B - \omega_2 B^2)}{1-B}X_t$$

f)
$$\frac{3B(1-\omega_1 B - \omega_2 B^2)}{1-B}X_t$$

Problem 11. The theoretical ACF of a purely seasonal ARIMA $(0,0,2)_{10}$ process will be non-zero only at the lags _____

- **a**) 1, 2, 10, 20
- **b**) 10, 20, 30, 40, ...
- **c**) 1, 2, 10, 20, 30, 40, ...
- **d**) 1, 2, 10, 11, 12, 13, ...
- **e**)★ 10, 20
 - **f**) 20
- **g**) 10, 11, 12, 13, ...

Problem 12. For an AR(1) process $z_t = C + \phi_1 z_{t-1} + a_t$, if you are given \mathcal{I}_n (information up to time n), the forecast \widehat{z}_{n+2} is _____

$$\mathbf{a})\star C + \phi_1 C + \phi_1^2 z_n$$

b)
$$C - \phi_1 a_n - \phi_1 a_{n-1}$$

- c) $C \phi_1 a_n$
- $\mathbf{d}) C + z_n$
- $\mathbf{e})$ C
- \mathbf{f}) z_n
- $\mathbf{g}) \ \phi_1 z_n$

Problem 13. Suppose the series $\{X_t\}$ and $\{Y_t\}$ are jointly stationary and we wish to construct a transfer function model $Y_t = C + v(B)X_t + N_t$. In the pre-whitening process, the goal is to apply a filter f(B) to both X_t and Y_t to produce new series $X'_t = f(B)X_t$ and $Y'_t = f(B)Y_t$ such that

- a) X'_t and Y'_t are uncorrelated
- **b**) X'_t and Y'_t are jointly stationary
- c) X'_t and Y'_t are independent
- d) their CCF is close to zero
- e) both X'_t and Y'_t are white noise
- \mathbf{f})* X'_t is white noise
- **g**) Y'_t is white noise

The AR-polynomial of an ARIMA $(2,0,1)(1,0,2)_{12}$ process is _____ Problem 14.

$$a)\star (1 - \phi_1 B - \phi_2 B^2)(1 - \Phi_1 B^{12})$$

b)
$$1 - \phi_1 B - \phi_2 B^2 - \Phi_1 B^{12}$$

c)
$$(1 - \phi_1 B)(1 - \Phi_1 B^{12} - \Phi_2 B^{24})$$

d)
$$1 - \phi_1 B - \Phi_1 B^{12} - \Phi_2 B^{24}$$

e)
$$(1 - \phi_1 B - \phi_2 B^2)(1 - \Phi_1 B^{12} - \Phi_2 B^{24})$$

f)
$$1 - \phi_1 B - \phi_2 B^2 - \Phi_1 B^{12} - \Phi_2 B^{24}$$

g)
$$(1-B)^2(1-B^{12})(1-\phi_1B-\phi_2B^2)$$

Problem 15. $\nabla_s z_t = \underline{\hspace{1cm}}$

a)
$$(1-B)^s z_t$$
 b) $(B-1)^s z_t$ **c**) $(1-B)^t z_s$ **d**) $z_{t+s} - z_{t+s-1}$

(B - 1)
$$^{s}z_{t}$$

c)
$$(1-B)^t z_s$$

d)
$$z_{t+s} - z_{t+s-1}$$

$$\mathbf{e}) \ z_{t+s} - z_t$$

$$\mathbf{f}) \star \ z_t - z_{t-s}$$

e)
$$z_{t+s} - z_t$$
 f)* $z_t - z_{t-s}$ g) $z_{t-s} - z_{t-s-1}$

Problem 16. The long range forecasts from a seasonal ARIMA model with seasonal lag S, orders of differencing d=0 and D=1, and a non-zero constant $C\neq 0$ will converge to ______

- \mathbf{a})* a repeating pattern (with period S) added to a straight line with non-zero slope
- b) a repeating pattern with period S
- c) a straight line with non-zero slope
- d) the estimated mean of the process
- e) the estimated variance of the process
- f) a value depending mainly on the last values of the series
- g) a straight line with slope depending mainly on the last values of the series

Suppose you are given a time series X_1, X_2, \ldots, X_n . You decide to log transform Problem 17. the data and work with the transformed series $Y_t = \log X_t$. You find a good ARIMA model for Y_t and use this to forecast the value Y_{n+5} . SAS gives you a 95% confidence interval (L, U) for Y_{n+5} . From this you can obtain a 95% confidence interval for X_{n+5} . What is this confidence interval?

a)
$$(e^{\mu}, e^{\mu + \sigma^2/2})$$

b)
$$(L - 1.96\sigma, U + 1.96\sigma)$$

$$\mathbf{c}$$
) $(\log L, \log U)$

d)
$$(\sqrt{L}, \sqrt{U})$$
 e)* (e^L, e^U)

$$(e^L, e^U)$$

f)
$$(L^2, U^2)$$

Problem 18. The next table gives the estimation output from fitting a certain model using PROC ARIMA. By very carefully reading this table, one can determine the model that was fit. What is the SAS code for specifying this model? Circle the correct response below.

- a) P=(1,2,10) Q=(3)
- $b) \star P = (1,2)(10) Q = (3)$
 - c) P=(1,2)(10) Q=(1)
 - \mathbf{d}) P=(1,2,10) Q=(1)
 - e) P=(1,2,10) Q=3
 - f) P=3 Q=1
 - g) P=(3) Q=(1)
 - h) P=10 Q=3

The SAS System

The ARIMA Procedure

Maximum Likelihood Estimation					
Parameter	Estimate	Standard Error	t Value	Approx Pr > t	Lag
MU	6.72100	0.23875	28.15	<.0001	0
MA1,1	-0.32195	0.10667	-3.02	0.0025	3
AR1,1	1.30023	0.07129	18.24	<.0001	1
AR1,2	-0.67083	0.07549	-8.89	<.0001	2
AR2,1	0.36009	0.09234	3.90	<.0001	10

Problem 19. A transfer function has v-weights given in the table below:

This can be expressed as a rational distributed lag model with particular values of b, h, and r (i.e., the delay, numerator order, and denominator order) as described in lecture. What are these values?

- a) b = 3, h = 5, r = 0
- **b**) b = 3, h = 5, r = 1
- c) b = 2, h = 6, r = 0
- **d**) b = 2, h = 6, r = 1
- $\mathbf{e}) \star \ b = 2, h = 4, r = 0$
- f) b = 2, h = 4, r = 1
- **g**) b = 2, h = 6, r = 2
- **h**) b = 2, h = 5, r = 2

Problem 20. The table immediately following this problem gives the ACF of a stationary process with seasonality s=8. The ACF is exactly zero for all lags from 11 onward. What type of ARIMA process is this?

- a) $(2,0,0)(1,0,0)_8$
- **b**) $(1,0,0)(2,0,0)_8$
- $(0,0,2)(0,0,5)_8$

- **d**) $(0,0,2)(5,0,0)_8$
- $(2,0,0)(0,0,5)_8$
- \mathbf{f})* $(0,0,2)(0,0,1)_8$

- $\mathbf{g}) (0,0,2)(1,0,0)_8$
- **h**) $(2,0,0)(5,0,0)_8$
- $\mathbf{i}) (2,0,0)(0,0,1)_8$

LAG	ACF
1	-0.261194
2	-0.223881
3	0.0
4	0.0
5	0.0
6	-0.098771
7	-0.115233
8	0.441176
9	-0.115233
10	-0.098771
11	0.0
12	0.0

The next two problems concern this situation: Suppose $\{z_t\}$ is an ARIMA process generated by the random shocks $\{a_t\}$. We observe **all** the values z_t and a_t up to time n. Call this set of information \mathcal{I}_n :

$$\mathcal{I}_n = \{z_n, z_{n-1}, z_{n-2}, \dots, a_n, a_{n-1}, a_{n-2}, \dots\}$$

We define $\widehat{z}_t = E(z_t | \mathcal{I}_n)$ and $\widehat{a}_t = E(a_t | \mathcal{I}_n)$.

Problem 21. Which of the following statements about \hat{z}_t is always true?

- a) $\hat{z}_t = \mu_z$ for t > n
- **b**) $\hat{z}_t = 0$ for $t \leq n$
- c) $\hat{z}_t = 0$ for t > n
- **d**) $\hat{z}_t = z_t \text{ for } t > n$
- e) $\hat{z}_t = \mu_z$ for $t \le n$
- \mathbf{f})* $\hat{z}_t = z_t \text{ for } t \leq n$

Problem 22. Which of the following statements about \hat{a}_t is always true?

- a) $\hat{a}_t = 0$ for $t \le n$ and $\hat{a}_t = \sigma_a^2$ for t > n
- **b**) $\widehat{a}_t = a_t$ for $t \le n$ and $\widehat{a}_t = z_t$ for t > n
- c) $\widehat{a}_t = \sigma_a^2$ for t = n and $\widehat{a}_t = 0$ for $t \neq n$
- $\mathbf{d})\star \ \widehat{a}_t = a_t \text{ for } t \leq n \text{ and } \widehat{a}_t = 0 \text{ for } t > n$
- e) $\hat{a}_t = 0$ for $t \le n$ and $\hat{a}_t = a_t$ for t > n
- f) $\widehat{a}_t = z_t$ for $t \le n$ and $\widehat{a}_t = a_t$ for t > n
- **g**) $\widehat{a}_t = \sigma_a^2$ for $t \leq n$ and $\widehat{a}_t = 0$ for t > n

Problem 23. If $\{X_t\}$ and $\{Y_t\}$ are jointly stationary, then the cross-correlation function is defined by $\rho_{xy}(s) = \dots$

- a) $Corr(X_{t-s}, Y_{t-s})$
- **b**) $Corr(X_{t+s}, Y_{t+s})$
- $\mathbf{c}) \operatorname{Corr}(X_{t+s}, Y_t)$
- **d**) $Corr(X_{t+s}, Y_{t-s})$
- $\mathbf{e})\star \operatorname{Corr}(X_t,Y_{t+s})$
 - \mathbf{f}) Corr (X_{t-s}, Y_{t+s})

The following two questions involve this situation:

Based on time series data $Y_1, Y_2, \ldots, Y_{100}$, SAS has fit an ARIMA model and produced forecasts for future values of Y_t . A fragment of SAS output is given below.

	Obs	Forecast	Std Error	95% Confidence Limits	
ĺ	101	6.5068	1.2111	4.1331	8.8804
ĺ	102	6.8077	1.2429	4.3716	9.2437

We are interested in forecasts for time t = 102. Assuming the model is correct and the parameter estimates are accurate, based on this output we can say that Y_{102} is normally distributed with a mean of $\mu = |$ and a standard deviation of $\sigma = |$.

Problem 24. Circle the correct value of μ .

- $a) \star 6.8077$
- **b**) 1.2429
- **c**) 4.3716
- **d**) 9.2437

- **e**) 6.5068
- **f**) 1.2111
- **g**) 4.1331
- **h**) 8.8804

Problem 25. Circle the correct value of σ .

- a) 6.8077
- **b**)* 1.2429
- **c**) 4.3716
- **d**) 9.2437

- e) 6.5068
- **f**) 1.2111
- **g**) 4.1331
- **h**) 8.8804

Problem 26. For an ARIMA(p, d, q) process $\{z_t\}$, the variance of the one-step-ahead prediction errors ...

- **a**) is equal to σ_z^2 . **b**) depends on ϕ_1, \dots, ϕ_p , and σ_a^2 . **c**) \star is equal to σ_a^2 . **d**) depends on d. **e**) depends on $\theta_1, \dots, \theta_q$. **f**) depends on d, ϕ_1, \dots, ϕ_p , and σ_z^2 .

Problem 27. The minimum information criterion (MINIC) method can tentatively identify the order of a stationary and invertible ARMA process. For a range of values for p and q, a table supplies an estimate of the $___$ divided by n (the series length) that would be obtained if an ARMA(p,q) model were fit to the data. The models with the _____ tabled values are worth considering as possible models.

The sentences above contain two blanks. Select the response below which gives two words which correctly fill these blanks.

- a) P-value, smallest
- **b**) *P*-value, largest
- c) AIC, smallest
- d) AIC, largest

- e)★ BIC, smallest f) BIC, largest
- g) Chi-Square, smallest h) Chi-Square, largest